

Lecture Series on
Intelligent Control

Lecture 24
Evolutionary Strategies and Evolutionary Programming

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Evolutionary Strategies and Evolutionary Programming

A bit of history

• **EVOLUTION STRATEGIES**

- Rechenberg, Schwefel,
- Technical University of Berlin, 1963
- https://en.wikipedia.org/wiki/Ingo_Rechenberg



• **EVOLUTIONARY PROGRAMMING**

- L. Fogel,
- "Artificial Intelligence Through Simulated Evolution"
- https://en.wikipedia.org/wiki/Lawrence_J._Fogel



- Are they really distinct?

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INDIVIDUALS AND POPULATIONS

- An individual stands for an alternative or a solution
- An individual is represented by a real-valued vector
(but in modern models it can also be an integer-valued or mixed integer-valued vector)
- A population is a set of individuals considered belonging to a same generation
- Offsprings are individuals (alternatives, solutions) derived from other solutions by means of *mutation* and *recombination*
- Fitness is a measure of adaptation to an environment or landscape - defined by the objective function in classical optimization

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ES GENERAL PROCESS

- Generate initial population of μ individuals
- Evaluate fitness of the existing μ individuals
- DO
 - Generate, from existing μ individuals, λ offspring (use recombination, then mutation)
 - Evaluate fitness of new individuals
 - Select μ survivors to form the next generation
- LOOP *until termination criterion is met*

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$(\mu \text{ and } \lambda)$ ES EVOLUTION STRATEGIES

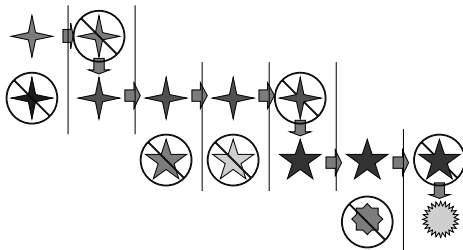
- (μ, λ) ES - an evolutionary process where a population with μ individuals (parents) originates λ descendents (children), from which μ are selected to form a new population (a new generation).
- $(\mu + \lambda)$ ES - an evolutionary process where a population with μ individuals (parents) originates λ descendents (children); and from the set of $\{\mu + \lambda\}$ individuals, μ are selected to form a new population (a new generation).
- Children are created by mutation and recombination.

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THE FIRST: $(1+1)$ ES

- The first historical model was a $(1+1)$ ES: 1 parent, 1 offspring, fitness calculated for both, the best one selected (offspring generated by mutation).

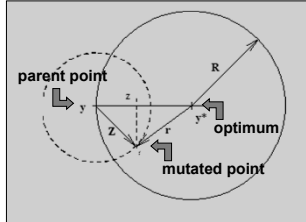


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The spherical model

- An isotropic fitness landscape $F_1(\mathbf{y}) = \sum_{i=1}^n (y_i - y_i^*)^2$
- Mutated point $\tilde{\mathbf{y}} = \mathbf{y} + \mathbf{Z}$
- \mathbf{Z} is a random vector
- R is the radius of the domain of success of mutations
- Rate of progress $\phi = E\{R-r\}$



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THE FIRST: (1+1) ES

- The selection scheme of the (1+1)ES is elitist.
The mutation scheme is based on Gaussian mutations.
- A solution \mathbf{X} is a vector with n real components
- A mutation is obtained by adding a random vector \mathbf{Z}
- Each component is mutated according to a Gaussian distribution with 0 mean and variance 1
- σ is the *step size* or *mutation strength*

x_1	x_2	...	x_n
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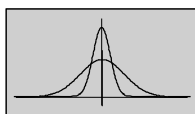
$$\mathbf{Z} = \sigma(N_1(0,1), \dots, N_n(0,1))^T$$

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The 1/5 Rule

- To reach the optimum, the mutation strength σ cannot remain constant
- The 1/5 Rule (Rechenberg): the Success Rate $S(h)$ (ratio between successful mutations and all mutations) must be close to 1/5
- If $S(h) > 1/5$ in the last h generations \Rightarrow increase σ
- If $S(h) < 1/5$ in the last h generations \Rightarrow decrease σ



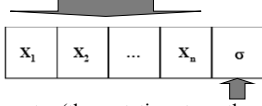
- Optimal value for h : $h = 10n$
- (n - dimension of the search space)

$$\mathbf{Z} = \sigma(N_1(0,1), \dots, N_n(0,1))^T$$

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The (1,λ) ES

- In the (1,λ) ES, 1 individual mutates to generate λ offspring and only 1 of these survives to the next generation. (parent and children do not compete)
 - Each individual is formed of n object parameters (the variables)
- 
- and one strategic parameter (the mutation strength, equal for all individuals)

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The σSA (1,λ) ES

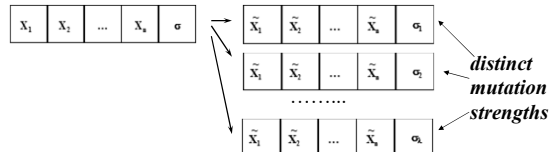
- σSA, a self-adapting scheme: the mutation strength evolves and is subject to selection
 - The object parameters are added with Gaussian perturbations, but...
 - The strategic parameter is subject to a multiplicative mutation
- $$\sigma_k^{(g+1)} = \xi \sigma^{(g)}$$
- $\xi = e^{zN(0,1)}$
- ξ is a random number with $E\{\xi\}=1$
 - ξ may follow a lognormal distribution
 - or a symmetrical two-point distribution

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The σSA (1,λ) ES

- Each descendent has a distinct mutation strength



- The selection process also selects the most favorable mutation strength...

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The σ SA (1, λ) ES

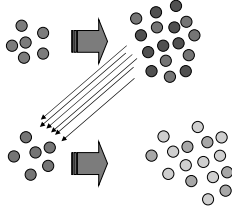
- How to select the learning parameter τ ? $\xi = e^{\tau V(0,1)}$
 - Schwefel's rule: $\tau \sim (n)^{-1/2}$, with n being the dimension of the search space
- A model like this displays a linear convergence order
 - with nearly optimum convergence rate

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The σ SA (μ,λ) ES

- The (μ,λ) ES is a natural extension of the (1, λ) ES
- One may select individuals randomly to reproduce, or
- one may give preference to the most fit, by:
 - tournament selection
 - roulette selection

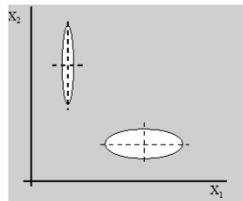


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Search patterns in σ SA (μ,λ) ES

- Instead of a single strategic parameter, one may have a mutation strength associated with each variable
- Mutations in the variables of an individual are uncorrelated: they adapt to an anisotropic fitness landscape, but search proceeds along coordinate axes



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$(\mu+\lambda)$ ES: Evolutionary Programming

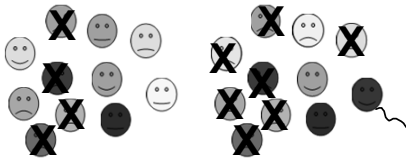
- Make $\mu = \lambda$ - this ES becomes EP!
- Major historical difference: German researchers gave preference to elitist selection, while Fogel followers adopted Stochastic Tournament (inspired by GA?)
- Simple Stochastic Tournament:
 - Randomly select two individuals
 - Compare fitness
 - Select to survive (to be reproduced) the best fit, with a given high probability
 - Repeat until λ individuals are selected

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Evolutionary Programming

- Generate Initial Population
- Replicate the Population and Mutate the offspring**
Compute fitness and Select Best Individuals



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EP and self adaptation

- Self-adaptation schemes have been adopted in EP.
- However, instead of Lognormal mutations, EP has traditionally adopted Gaussian mutations, still multiplicative

$$\sigma^{(g+1)} = \xi \sigma^{(g)} \quad \xi = 1 + \tau N(0,1)$$

- But...
- it has been shown that this EP scheme is an approximation of the general ES scheme using the Lognormal distribution

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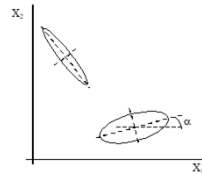
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Enhancing the mutation scheme

- New strategic parameters:
- correlation between mutations
- this allows a more robust search
- pattern in complex landscapes

$$\tilde{\mathbf{X}} = \mathbf{X} + \mathbf{C}\mathbf{Z}$$

- Z is a random vector and C is a Matrix defining a Mahalanobis metric in space - it may be defined by elementary angles α , subject to mutations
- https://en.wikipedia.org/wiki/Mahalanobis_distance



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Recombination: $(\mu/\rho, \lambda)$ ES

- Recombination: mixing ρ individuals (among μ parents) to obtain a new one
- Biology is based on $\rho = 2$ but... why stop at 2?
- Recombination variants:
 - uniform crossover
 - intermediary recombination
 - global
 - local
 - point crossover

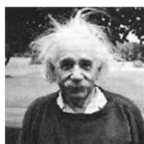
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The importance of recombination

Max the success in life f
 $f(x,y) = x^2 + y^2 \quad x,y \in [0,100]$

45 38
 X (Intelligence) Y (Beauty)



100 14

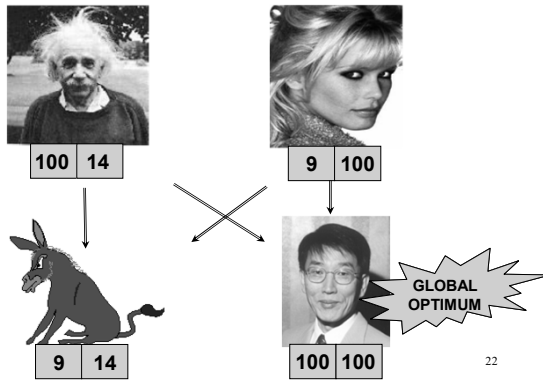


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The importance of recombination



Recombination variants

- Uniform crossover: a new individual is formed by randomly selecting each component from a different parent.

15	28	-7	...	45
33	-2	33	...	78
43	12	-8	...	73
43	-2	-8	...	45

- Example for $\rho = 3$

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Recombination variants

- Intermediary recombination: each variable in the new individual is a combination of the values of the same variable in the ρ parents
 - *there are many variants of intermediary recombination*

- Example for $\rho = 2$: for the variable k ,

$$x_k^{new} = u_k x_{k,j1} + (1 - u_k) x_{k,j2}$$

- where u_k is a random number sampled from a uniform distribution in $[0,1]$

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Recombination variants

- Point crossover: the parents are sliced in parts (defined by randomly selecting γ points, common to all parents) and the new individual receives a part from each parent, in turns
 - this is what happens in Genetic Algorithms, for $p = 2$

15	28	-7	66	45	18	7	-7	33	44	14	20	11	77	82
12	14	-2	-4	-1	15	2	-6	33	45	15	23	-8	77	80
35	28	-7	61	41	17	3	-7	38	41	19	28	-7	56	76
15	28	-7	-4	-1	15	2	-6	33	45	15	28	-7	56	76

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Handling constraints

- As in all evolutionary algorithms...
- By controlling mutations so that no unfeasible individuals are generated
- By applying penalties to the fitness value of unfeasible individuals

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Starting point

- Typically:
- By randomly generating the coordinates of the μ first individuals
- By generation mutations from a seed or initial individual

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Conclusions

- Evolution Strategies, as a general algorithmic approach, is very successful
- Among Evolutionary Algorithms, it ranks in a high place - there are many reports and examples where an ES model has performed better than a Genetic Algorithm model
- There is, however, no demonstration of definite superiority - ultimately, it depends in a high degree of the skill and cleverness of the engineer or the scientist, when developing the model

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