

2.5 :

$$\textcircled{a} : v(t) = 227 \times \sqrt{2} \cos(\omega t + 30^\circ) = 391.7 \cos(\omega t + 30^\circ) \text{ V}$$

$$\textcircled{b} : \tilde{I} = \frac{\tilde{V}}{20} = 13.89 \angle 30^\circ \text{ A}$$

$$i(t) = 19.58 \cos(\omega t + 30^\circ) \text{ A}$$

$$\textcircled{c} : Z = j\omega L = j(2\pi \times 60)(10 \times 10^{-3}) = 3.771 \angle 90^\circ \Omega$$

$$\tilde{I} = \frac{\tilde{V}}{Z} = \frac{227 \angle 30^\circ}{3.771 \angle 90^\circ} = 73.46 \angle -60^\circ \text{ A}$$

$$i(t) = 73.46 \times \sqrt{2} \cos(\omega t - 60^\circ) = 103.9 \cos(\omega t - 60^\circ) \text{ A}$$

$$\textcircled{d} : Z = -j25 \Omega$$

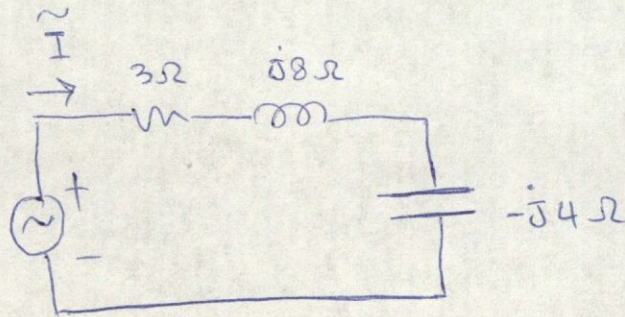
$$\tilde{I} = \frac{\tilde{V}}{Z} = \frac{227 \angle 30^\circ}{25 \angle -90^\circ} = 11.08 \angle 120^\circ \text{ A}$$

$$i(t) = 11.08 \times \sqrt{2} \cos(\omega t + 120^\circ) = 15.67 \cos(\omega t + 120^\circ) \text{ A}$$

$$\underline{2.7} \text{ :}$$

(a) :

$$100 \angle 0^\circ$$



(b) : $Z = 3 + j8 - j4 = 3 + j4 = 5 \angle 53.1^\circ \Omega$

(c) : $\tilde{I} = \frac{100 \angle 0^\circ}{5 \angle 53.1^\circ} = 20 \angle -53.1^\circ \text{ A}$

The current lags by 53.1° .

$$P.F. = \cos(53.1^\circ) = 0.6$$

2.11 :

(3)

(a): $P(t) = v(t) \cdot i(t) = 391.7 \times 19.58 \cos^2(\omega t + 30^\circ)$

$$= 0.7669 \times 10^4 \times \left(\frac{1}{2}\right) [1 + \cos(2\omega t + 60^\circ)]$$

$$= 3.834 \times 10^3 + 3.834 \times 10^3 \cos(2\omega t + 60^\circ) \text{ Watt}$$

$$P = VI \cos(\theta_V - \theta_I) = 277 \times 13.85 \cos(0^\circ) = 3.836 \text{ kW}$$

$$Q = VI \sin(\theta_V - \theta_I) = 0 \text{ VAR}, \quad P.F. = \cos(0^\circ) = 1$$

(b): $P(t) = v(t) \cdot i(t) = 391.7 \times 103.9 \cos(\omega t + 30^\circ) \cos(\omega t - 60^\circ)$

$$= 4.07 \times 10^4 \times \frac{1}{2} \times [\cos(90^\circ) + \cos(2\omega t - 30^\circ)]$$

$$= 2.035 \times 10^4 \cos(2\omega t - 30^\circ) \text{ W}$$

$$P = VI \cos(\theta_V - \theta_I) = 277 \times 73.46 \cos(30^\circ + 60^\circ) = 0 \text{ W}$$

$$Q = VI \sin(\theta_V - \theta_I) = 277 \times 73.46 \sin(90^\circ) = 20.35 \text{ KVAR}$$

$$P.F. = \cos(90^\circ) = 0 \quad \text{Lagging.}$$

④

$$\begin{aligned} \textcircled{c}: P(t) &= V(t) \cdot i(t) = 391.7 \times 15.67 \cos(\omega t + 30^\circ) \cos(\omega t + 120^\circ) \\ &= 6.138 \times 10^3 \times \frac{1}{2} [\cos(-90^\circ) + \cos(2\omega t + 150^\circ)] \\ &= 3.069 \times 10^3 \cos(2\omega t + 150^\circ) \text{ W} \end{aligned}$$

$$P = VI \cos(\theta_V - \theta_I) = 277 \times 11.08 \cos(30^\circ - 120^\circ) = 0 \text{ watt}$$

$$Q = VI \sin(\theta_V - \theta_I) = 277 \times 11.08 \sin(-90^\circ) = -3.069 \text{ KVAR}$$

$$P.F. = \cos(\theta_V - \theta_I) = \cos(-90^\circ) = 0 \quad \text{Leading.}$$

2.12 :

$$\begin{aligned} \textcircled{a}: P_R(t) &= 678.8 \times 67.88 \cos^2(\omega t + 45^\circ) \\ &= 4.608 \times 10^4 \times \frac{1}{2} [1 + \cos(2\omega t + 90^\circ)] \\ &= 2.304 \times 10^4 + 2.304 \times 10^4 \cos(2\omega t + 90^\circ) \quad \omega \end{aligned}$$

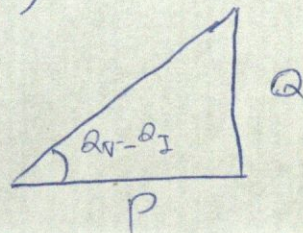
$$\begin{aligned} \textcircled{b}: P(t) &= [678.8 \cos(\omega t + 45^\circ)] [27.15 \cos(\omega t + 45^\circ + 90^\circ)] \\ &= 1.843 \times 10^4 \cos(\omega t + 45^\circ) \cos(\omega t + 135^\circ) \\ &= 1.843 \times 10^4 \times \frac{1}{2} [\cos(-90^\circ) + \cos(2\omega t + 180^\circ)] \\ &= 9.215 \times 10^3 \cos(2\omega t + 180^\circ) = -9.215 \cos(2\omega t) \quad \omega \end{aligned}$$

$$\textcircled{c}: P = \frac{\tilde{V}_{rms}^2}{R} = \frac{\left(\frac{678.8}{\sqrt{2}}\right)^2}{10} = 2.304 \times 10^4 \quad \omega$$

$$\textcircled{d}: Q = \frac{\tilde{V}_{rms}^2}{X} = \frac{\left(\frac{678.8}{\sqrt{2}}\right)^2}{25} = 9.215 \times 10^3 \quad \text{VAR}$$

$$\textcircled{e}: \theta_V - \theta_I = \tan^{-1}\left(\frac{Q}{P}\right) = \tan^{-1}\left(\frac{9.215 \times 10^3}{2.304 \times 10^4}\right) = 21.8^\circ$$

$$P.F. = \cos(\theta_V - \theta_I) = 0.928 \text{ Leading}$$



2.25 8

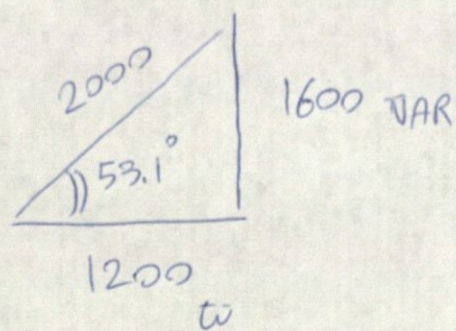
(2)

$$S_R = \tilde{V}_R \tilde{I}_R^* = R \tilde{I} \tilde{I}^* = R |\tilde{I}|^2 = 3 \times 20^2 = 1200 + j0$$

$$S_L = \tilde{V}_L \tilde{I}^* = Z_L \tilde{I} \tilde{I}^* = jX_L |\tilde{I}|^2 = j8 \times 20^2 = 0 + j3200$$

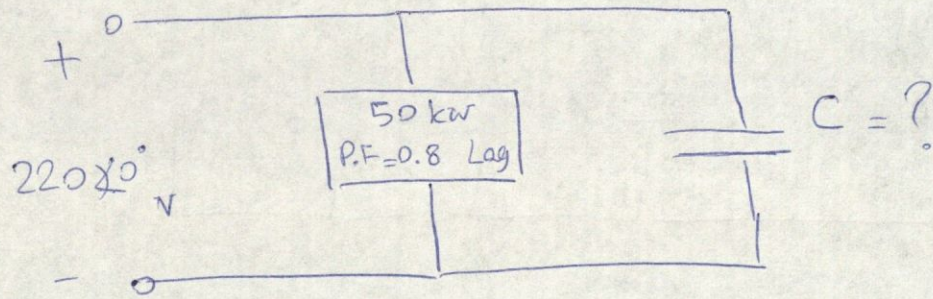
$$S_C = \tilde{V}_C \tilde{I}^* = Z_C \tilde{I} \tilde{I}^* = -jX_C |\tilde{I}|^2 = -j4 \times 20^2 = 0 - j1600$$

$$S_T = S_R + S_L + S_C = 2000 \angle 53.1^\circ$$



(3)

$$\underline{2.27} \text{ c}$$



$$P_{old} = 50 \text{ kW}, \cos^{-1} 0.8 = 36.87^\circ \Rightarrow \theta_{old} = 36.87^\circ$$

$$Q_{old} = V_{old} \times I_{old} \times \sin(\theta_{old}) = \underbrace{V_{old} \times I_{old} \times \cos(\theta_{old})}_{P_{old}} \times \frac{\sin(\theta_{old})}{\cos(\theta_{old})}$$

$$= P_{old} \times \tan(\theta_{old}) = 37.5 \text{ kVAR}$$

$$S_{old} = 50000 + j 37500, \quad \theta_{new} = \cos^{-1} 0.95 = 18.19^\circ$$

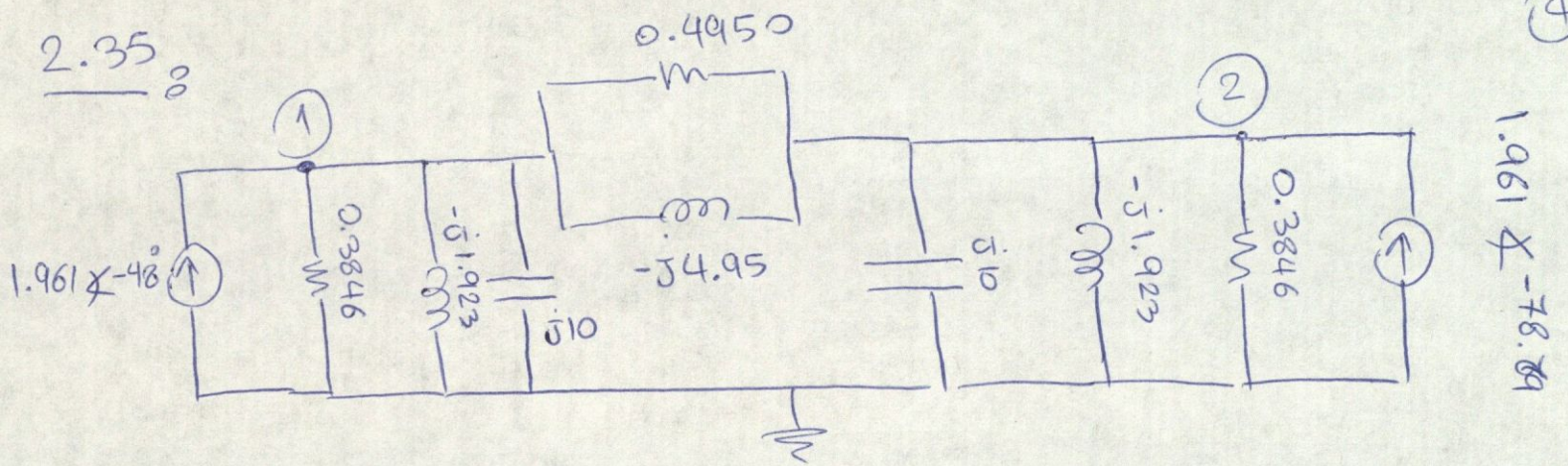
$$S_{new} = 50000 + j 50000 \tan(18.19) = 50000 + j 16430$$

$$S_{cap} = S_{old} - S_{new} = j 21070 \text{ VA}$$

$$C = \frac{21070}{(377)(220)^2} = 1155 \text{ } \mu\text{F}$$

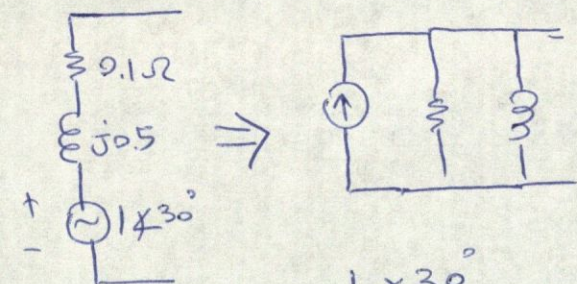
$$\frac{2.35}{2}$$

(4)



$$\begin{bmatrix} 0.3846 + 0.4950 + j(10 - 1.923 - 4.95) & -(0.495 - j4.95) \\ -(0.495 - j4.95) & 0.3846 + 0.495 + j(10 - 1.923 - 4.95) \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 1.961 \angle -48.69 \\ 1.961 \angle -78.69 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 0.8796 + j3.127 & -0.495 + j4.95 \\ -0.495 + j4.95 & 0.8796 + j3.127 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 1.961 \angle -48.69 \\ 1.961 \angle -78.69 \end{bmatrix}$$



$$\frac{1}{\underbrace{0.1 + j0.5}_Z} = \underbrace{0.3846 - j1.923}_Y$$

$$\frac{1 \angle 30^\circ}{0.1 + j0.5} = 1.961 \angle -48^\circ$$

$$\frac{1}{0.02 + j0.2} = 0.495 + (-j4.95)$$